

Partitioned Methods for Multifield Problems: *Exercise 3: Partitioned Approach: Iterative Methods*

Exercise 1:

(26 points)

Consider two coupled initial value problems:

$$\begin{aligned}\dot{u} &= au - (u + v)/2 \\ \dot{v} &= av + (u + v)/2,\end{aligned}$$

write and run a Matlab script for a numerical solution of the coupled problems in a partitioned way. Use Heun's scheme for the time discretization. Take $a = 0.1$, $u(0) = v(0) = 1$, and compute the solution in time period $t \in [0, 5]$. Use weak coupling and strong coupling and compare their error convergence rates (to evaluate error of the numerical solutions, compare them with the analytical solution $u(t) = e^{at} - te^{at}$ and $v(t) = e^{at} + te^{at}$). The coupled equilibrium system arises in the strong coupling can be solved by using Jacobi or Gauss-Seidel iterations.

The error for the comparison can be taken as the error of the solutions at $t = 5$. Use different time steps τ to solve the problems, and observe how fast the errors are reduced by reducing τ , plot the "error vs. τ " curves for weak and strong coupling schemes respectively (better use logarithmic scale to see the difference).

Which coupling scheme has the 2nd-order error convergence rate?

Exercise 2:

(10 points)

The block Jacobi method and the block Gauss-Seidel method shall be used to approximate a solution of the non-linear system

$$\begin{aligned}f(x, y) &= 0 \\ g(x, y) &= 0\end{aligned}$$

with $x, y \in \mathbb{R}$ and $f, g : \mathbb{R}^2 \rightarrow \mathbb{R}$. The Matlab code `block-jacobi.m` implements the block Jacobi method, at which a fixpoint iteration with a damping is used to solve each subproblem of the non-linear system. An example for the non-linear system is provided by the Matlab code `f-ex.m`. The Matlab script `main.m` applies the implemented block Jacobi method onto the example.

Plot the relative error over the number of iterations. Do you see convergence? If not, adapt the damping parameters α and β , so that a convergence is achieved.

Implement Block-Newton method to solve the coupled system, check the Matlab code `dfdx-ex.m` to know the sub-matrices of the full Jacobi matrix. The method uses only the sub-matrices, does not inverse the full Jacobi.

Plot the "error vs. iteration" curves for both methods and compare their error convergence rates.