

**Theses:**

**Plörer, P.**, Automated Vision-Based Rendezvous and Servicing of a Non-Cooperative Spacecraft using a Robotic Manipulator, Master's thesis, Technische Universität Braunschweig. Germany, 2024.

**Plörer, P.**, Attitude compensation for a Satellite while performing on-orbit activities, Study thesis, Technische Universität Braunschweig. Germany, 2022.